



# Quantum Integer Programming

**47-779**  
**Quadratic Unconstrained  
Binary Optimization (QUBO)**

**Carnegie Mellon University**  
Tepper School of Business

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# Quiz 3

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# Agenda

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- QUBO Definition
- QUBO - Ising Model Mapping
- QUBO - Integer Programming model
  - QUBO: Binarization
  - QUBO: Unconstraining
  - QUBO: Quadraticization
- Integer Programming as QUBO
- Coloring Example
- Integer Factorization



# QUBO model

## Quadratic Unconstrained Binary Optimization

$$\min_{\mathbf{x} \in \{0,1\}^n} \sum_{(ij) \in E(G)} x_i Q_{ij} x_j + \sum_{i \in V(G)} Q_{ii} x_i + c$$

$$= \min_{\mathbf{x} \in \{0,1\}^n} \mathbf{x}^T \mathbf{Q} \mathbf{x} + c$$

### Quadratic coefficient matrix $\mathbf{Q}$

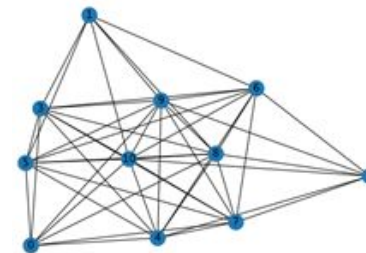
- Can be either upper triangular or complete  $x_i x_j = x_j x_i$
- Elements on diagonal can be linearized  $x_i^2 = x_i$  if  $x_i \in \{0, 1\}$
- Represents adjacency matrix of a problem

### Offset $c$

- Irrelevant for optimization

|      |      |      |      |      |      |      |      |       |       |       |
|------|------|------|------|------|------|------|------|-------|-------|-------|
| -46. | 0.   | 0.   | 48.  | 48.  | 48.  | 0.   | 48.  | 48.   | 48.   | 48.   |
| 0.   | -44. | 0.   | 48.  | 0.   | 48.  | 48.  | 0.   | 48.   | 48.   | 48.   |
| 0.   | 0.   | -44. | 0.   | 48.  | 0.   | 48.  | 48.  | 48.   | 48.   | 48.   |
| 48.  | 48.  | 0.   | -92. | 48.  | 96.  | 48.  | 48.  | 96.   | 96.   | 96.   |
| 48.  | 0.   | 48.  | 48.  | -92. | 48.  | 48.  | 96.  | 96.   | 96.   | 96.   |
| 48.  | 48.  | 0.   | 96.  | 48.  | -92. | 48.  | 48.  | 96.   | 96.   | 96.   |
| 0.   | 48.  | 48.  | 48.  | 48.  | 48.  | -91. | 48.  | 96.   | 96.   | 96.   |
| 48.  | 0.   | 48.  | 48.  | 96.  | 48.  | 48.  | -92. | 96.   | 96.   | 96.   |
| 48.  | 48.  | 48.  | 96.  | 96.  | 96.  | 96.  | 96.  | -139. | 144.  | 144.  |
| 48.  | 48.  | 48.  | 96.  | 96.  | 96.  | 96.  | 96.  | 144.  | -138. | 144.  |
| 48.  | 48.  | 48.  | 96.  | 96.  | 96.  | 96.  | 96.  | 144.  | 144.  | -139. |

In terms of IP it would be a  
 (possible non-convex if  $\mathbf{Q} \neq 0$ )  
 Integer Nonlinear Program





# QUBO - Ising Mapping

1-to-1 mapping between QUBO and Ising models using spin-binary bijection

$$\begin{aligned} \sigma_i &= 2x_i - 1 & x_i &= (\sigma_i + 1)/2 \\ \sigma_i \sigma_j &= 4x_i x_j - 2x_i - x_j + 1 & x_i x_j &= (\sigma_i \sigma_j + \sigma_i + \sigma_j + 1)/4 \end{aligned}$$

$$\begin{aligned} \min_{\sigma \in \{-1, +1\}^n} \sum_{(ij) \in E(G)} J_{ij} \sigma_i \sigma_j + \sum_{i \in V(G)} h_i \sigma_i + c_I &= \\ \min_{x \in \{0, 1\}^n} \sum_{(ij) \in E(G)} x_i Q_{ij} x_j + \sum_{i \in V(G)} Q_{ii} x_i + c_Q & \\ Q_{ij} = 4J_{ij}, Q_{ii} = 2h_i - \sum_{j \in V(G)} (2J_{ij} + 2J_{ji}), c_I = c_Q + \sum_{i < j} J_{ij} - \sum_{i \in V(G)} h_i & \end{aligned}$$



$$\begin{aligned} \min_{x \in \{0, 1\}^n} \sum_{(ij) \in E(G)} x_i Q_{ij} x_j + \sum_{i \in V(G)} Q_{ii} x_i + c_Q &= \\ \min_{\sigma \in \{-1, +1\}^n} \sum_{(ij) \in E(G)} J_{ij} \sigma_i \sigma_j + \sum_{i \in V(G)} h_i \sigma_i + c_I & \end{aligned}$$

$$J_{ij} = Q_{ij}/4, h_i = Q_{ii}/2 + \sum_{j \in V(G)} (Q_{ij}/4 + Q_{ji}/4), c_I = c_Q + \sum_{i < j} Q_{ij}/4 - \sum_{i \in V(G)} Q_{ii}/2$$



# QUBO as Integer Programs

$$\begin{aligned} & \min_{\mathbf{x} \in \{0,1\}^n} \sum_{(ij) \in E(G)} x_i Q_{ij} x_j + \sum_{i \in V(G)} Q_{ii} x_i + c \\ & = \min_{\mathbf{x} \in \{0,1\}^n} \mathbf{x}^\top \mathbf{Q} \mathbf{x} + c \end{aligned}$$

Although this is already solvable using INLP programming tools, we can reformulate it as a ILP by adding a variable  $x_{ij} = x_i x_j$  whose nonlinearity can be posed a linear inequalities.

Experimental results show this is the most efficient ILP formulation of the Ising problem

$$\begin{aligned} & \min_{\mathbf{x} \in \{0,1\}^n} \sum_{(ij) \in E(G)} Q_{ij} x_{ij} + \sum_{i \in V(G)} Q_{ii} x_i + c \\ & \text{s.t. } x_{ij} \geq x_i + x_j - 1, x_{ij} \leq x_i, x_{ij} \leq x_j \quad \forall (ij) \in E(G) \\ & x_i \in \{0, 1\} \quad \forall i \in V(G), x_{ij} \in \{0, 1\} \quad \forall (ij) \in E(G) \end{aligned}$$



# QUBO - Binarization

How to transform general Integer Programs into Binary programs?

$$y \in \{0, \dots, \bar{y}\} \subseteq \mathbb{Z}$$

In general with a width of the integer encoding  $d$

$$y = \sum_{j=1}^d k_j x_j = \mathbf{k}^\top \mathbf{x}, k_j \in \mathbb{Z}_+, x_j \in \{0, 1\}$$

- Unary encoding  $k_j = 1, d = \bar{y}$
- Binary encoding  $k_j = 2^{j-1}, d = \lfloor \log_2(\bar{y}) \rfloor$
- Bounded encoding

We can find an encoding with an upper bound for the coefficients  $\mu \ll \bar{y}$

$$\text{if } \bar{y} < 2^{\lfloor \log(\mu) \rfloor} + 1$$

$$\text{if } \bar{y} > 2^{\lfloor \log(\mu) \rfloor} + 1$$

$$\mathbf{k} = \left[ 2^0, 2^1, \dots, 2^{\lfloor \log(\bar{y}) \rfloor - 1}, \bar{y} - \sum_{i=1}^{\lfloor \log(\bar{y}) \rfloor} 2^{i-1} \right]$$

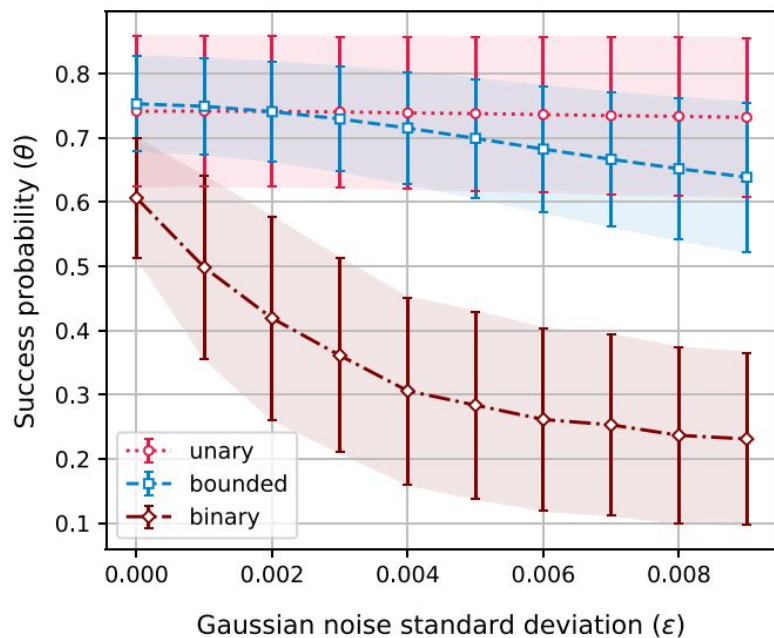
$$\rho = \lfloor \log \mu \rfloor + 1, v = \bar{y} - \sum_{i=1}^{\rho} 2^{i-1}, \text{ and } \eta = \left\lfloor \frac{v}{\mu} \right\rfloor$$

$$k_i = \begin{cases} 2^{i-1} & \text{for } i = 1, \dots, \rho \\ \mu & \text{for } i = \rho + 1, \dots, \rho + \eta \\ v - \eta\mu & \text{for } i = \rho + \eta + 1 \text{ if } v - \eta\mu \neq 0 \end{cases}$$

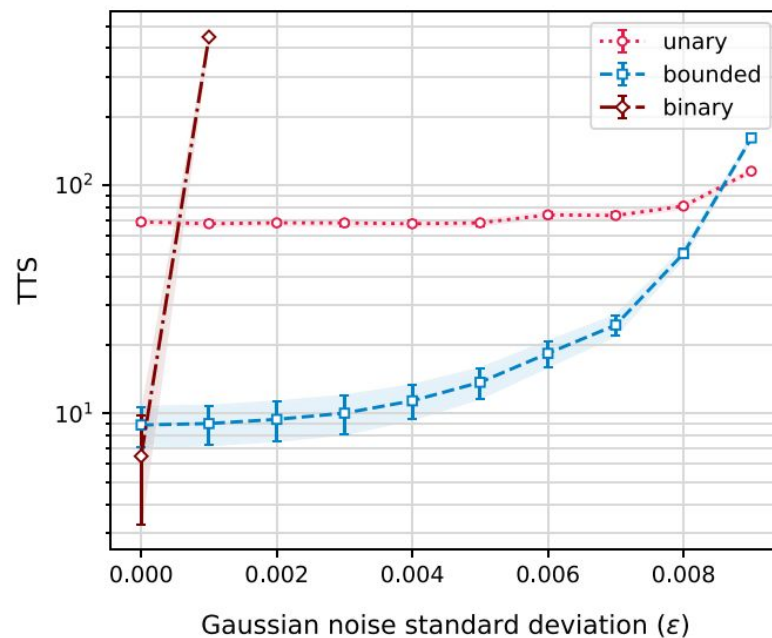


# QUBO - Binarization

$\mu \ll \bar{y}$  upper bound can be computed from the problem matrix and the resolution of the quadratic and linear terms in the machine



**(a)** The scaling of success probability as a function of the standard deviation of noise. The success probability  $\theta$  is reported averaged over the 128 UIQP instances of each noise parameter. The shaded stripe indicates the 50th percentile.



**(b)** The scaling of TTS as a function of the standard deviation of noise. Instances for which the optimal solution is never observed are ignored and the curves are discontinued if more than 15% of instances are never solved.





# QUBO - Pseudo-Boolean functions and Quadraticization

Any pseudo-Boolean function defined as

$$f : \{0, 1\}^n \mapsto \mathbb{R}$$

Can be written uniquely as a sum of multilinear functions

$$f(x) = a_0 + \sum_i a_i x_i + \sum_{ij} a_{ij} x_i x_j + \sum_{ijk} a_{ijk} x_i x_j x_k + \dots$$

We can transform any binary polynomial into a quadratic polynomial by introducing new variables as we saw before

Naive example:  $x_{ij} = x_i x_j$

- Using linear inequalities

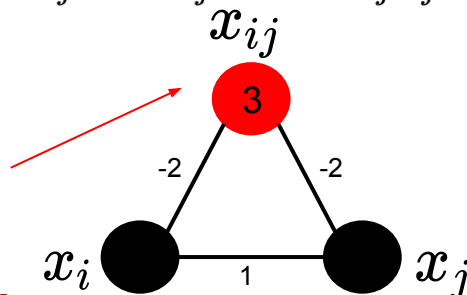
$$x_{ij} \geq x_i + x_j - 1, x_{ij} \leq x_i, x_{ij} \leq x_j$$

- Using a polynomial expression

$$H(\mathbf{x}) = 3x_{ij} + x_i x_j - 2x_{ij}x_i - 2x_{ij}x_j$$

- Graph:

Usually called ancillary variables



| $x_i$ | $x_j$ | $x_{ij}$ | $x_i x_j$ | $H(\mathbf{x})$ |
|-------|-------|----------|-----------|-----------------|
| 1     | 1     | 1        | 1         | 0               |
| 1     | 1     | 0        | 1         | 1               |
| 1     | 0     | 1        | 0         | 1               |
| 1     | 0     | 0        | 0         | 0               |
| 0     | 1     | 1        | 0         | 1               |
| 0     | 1     | 0        | 0         | 0               |
| 0     | 0     | 1        | 0         | 3               |
| 0     | 0     | 0        | 0         | 0               |

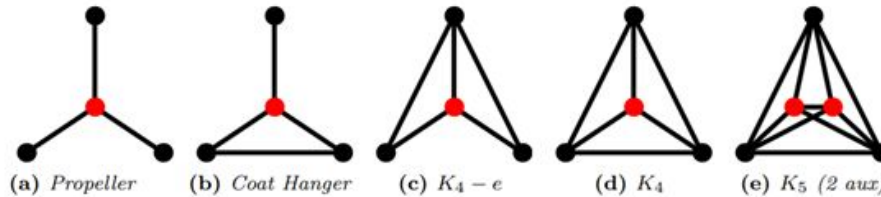


# QUBO - Quadraticization and logical functions

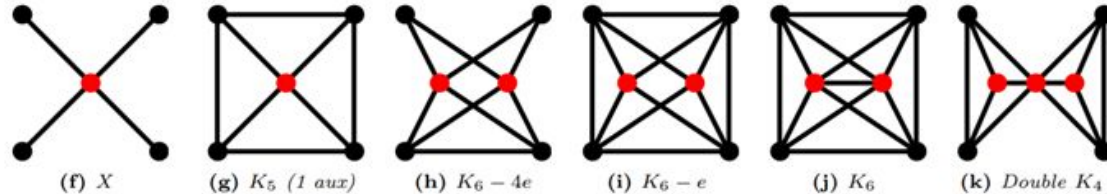
We can follow the previous reduction to obtain a Quadratically constrained program from any arbitrary problem.

There are many clever way of "Quadratizing" problems [1]

- Cubic



- Quartic



## Logical gates

AND:  $x_i \wedge x_j = x_i x_j = x_{ij} \mapsto 3x_{ij} + x_i x_j - 2x_{ij} x_i - 2x_{ij} x_j$

OR:  $x_i \vee x_j = x_i + x_j - x_i x_j = x_i + x_j - x_{ij} \mapsto x_i + x_j - 3x_{ij} - x_i x_j + 2x_{ij} x_i + 2x_{ij} x_j$

NOT:  $\neg x = y \mapsto 2xy - x - y$



# QUBO - Unconstraining

## Lagrange Multipliers

For LP problems we had

$$\begin{aligned} \min_{\mathbf{x} \geq 0} \mathbf{c}^\top \mathbf{x} \\ \text{s.t. } \mathbf{Ax} = \mathbf{b} \end{aligned} \iff \min_{\mathbf{x} \geq 0} \mathbf{c}^\top \mathbf{x} + \lambda^\top (\mathbf{b} - \mathbf{Ax})$$

Where determining the multipliers can be written as  
and where the following holds:

$$\begin{aligned} \max_{\lambda} \mathcal{L}(\lambda) = \max_{\lambda} \lambda^\top \mathbf{b} \\ \text{s.t. } \lambda^\top \mathbf{A} \leq \mathbf{c}^\top \end{aligned}$$

$$\text{Strong duality: } \lambda^{*\top} \mathbf{b} = \mathbf{c}^\top \mathbf{x}^*$$

For IP problems, strong duality does not hold, but we can still use the multipliers to convert the problem into unconstrained

$$\begin{aligned} \min_{\mathbf{x} \in \{0,1\}^n} \mathbf{c}^\top \mathbf{x} \\ \text{s.t. } g(\mathbf{x}) \leq 0 \quad (\lambda) \\ h(\mathbf{x}) = 0 \quad (\rho) \end{aligned} \iff \min_{\mathbf{x} \in \{0,1\}^n} \mathbf{c}^\top \mathbf{x} + \lambda^\top g(\mathbf{x}) + \rho^\top h(\mathbf{x})$$

where  $\lambda_i^\top \geq 0$



# QUBO - Unconstraining

We can transform any arbitrary constraint in terms of binaries into multilinear, and then quadratize them.

We can then transform inequalities into equalities by introducing slack variables, which by scaling the constraints become integers

Finally we can binarize these slacks

$$\begin{array}{lll}
 \min_{\mathbf{x} \in \{0,1\}^n} \mathbf{c}^\top \mathbf{x} & \min_{\mathbf{y} \in \{0,1\}^n} \mathbf{d}^\top \mathbf{y} & \min_{\mathbf{y} \in \{0,1\}^n, \mathbf{s} \in \mathbb{Z}_+} \mathbf{d}^\top \mathbf{y} \\
 \text{s.t. } g(\mathbf{x}) \leq 0 & \text{s.t. } \mathbf{y}^\top G \mathbf{y} \leq 0 \quad (\lambda) & \text{s.t. } \mathbf{y}^\top G \mathbf{y} + \mathbf{s} = 0 \quad (\lambda) \\
 h(\mathbf{x}) = 0 & \mathbf{y}^\top H \mathbf{y} = 0 \quad (\rho) & \mathbf{y}^\top H \mathbf{y} = 0 \quad (\rho)
 \end{array}$$

Considering that we can only deal with discrete variable in QUBO, we cannot change the value of the multipliers.

- Set the multipliers to be constant penalty factor!
- Example: Integer linear inequalities become penalties by “squaring” them

$$\begin{array}{l}
 \min_{\mathbf{x} \in \mathbb{Z}_+} \mathbf{c}^\top \mathbf{x} \implies \min_{\mathbf{x} \in \mathbb{Z}_+, \mathbf{s} \in \mathbb{Z}_+} \mathbf{c}^\top \mathbf{x} + \rho^\top (\mathbf{A}\mathbf{x} + \mathbf{s} - \mathbf{b})^\top (\mathbf{A}\mathbf{x} + \mathbf{s} - \mathbf{b}) \\
 \text{s.t. } \mathbf{A}\mathbf{x} \leq \mathbf{b}
 \end{array}$$



# QUBO - Unconstraining

## Penalty factor

In general, we represent the constrained problem with a feasible region

$$F = \bigcap_j F_j = \bigcap_j \{ \mathbf{x} \in \{0, 1\}^n : g_j(\mathbf{x}) \leq 0 \}$$

We are mapping it into a QUBO problem

$$\min_{\mathbf{y} \in \{0,1\}^n} \sum_{(ij) \in E(G)} y_i Q_{ij} y_j + \sum_{i \in V(G)} Q_{ii} y_i + c_Q$$

Where the  $\mathbf{y}$  variables include both the original variables  $\mathbf{x}$  and ancillas  $\mathbf{a}$

The penalization factor for each constraint should read

$$\min_{\mathbf{a}} Pen_{F_j}(\mathbf{x}, \mathbf{a}) \begin{cases} = 0 & \text{if } \mathbf{x} \in F_j \\ \geq g & \text{if } \mathbf{x} \notin F_j \end{cases}$$

Where  $g > 0$  is the gap between feasible and infeasible solutions.

Therefore we could in general find  
but in practice this becomes an  
MILP and its as tough to solve as  
the original QUBO

$$\begin{aligned} & \max_{g, Q, c_Q} g \\ & \text{s.t. } \mathbf{y}^\top Q \mathbf{y} + c_Q \geq 0 \quad \forall \mathbf{x} \in F, \forall \mathbf{a} \\ & \mathbf{y}^\top Q \mathbf{y} + c_Q \geq g \quad \forall \mathbf{x} \notin F, \forall \mathbf{a} \\ & \exists \mathbf{a} : \mathbf{y}^\top Q \mathbf{y} + c_Q = 0 \quad \forall \mathbf{x} \in F \\ & \underline{Q} \leq Q \leq \overline{Q}, \underline{c_Q} \leq c_Q \leq \overline{c_Q} \end{aligned}$$



# QUBO - Examples

## Binary Linear Programming

$$\min_{\mathbf{x} \in \{0,1\}^n} \mathbf{c}^\top \mathbf{x}$$

$$s. t. \mathbf{Ax} = \mathbf{b}$$

We can write the energy function in two terms  $H = H_A + H_B$

- Constraint satisfaction ( $H_A = 0$ )

$$H_A = \rho \sum_{j=1}^m \left( \sum_{i=1}^n A_{ij} x_i - b_j \right)^2$$

- Objective function

$$H_B = \sum_{i=1}^n c_i x_i$$

How to determine the penalty? Guarantee that the minimal change in infeasibility is larger than the maximal case in objective

$$\rho \geq \frac{\Delta H_B^{\max}}{\Delta H_A^{\min}} \quad \Delta H_B^{\max} = \sum_{i=1}^n \max\{c_i, 0\}$$

$$\Delta H_A^{\min} = \min_{\sigma_i \in \{0,1\}, j} \left( \max \left[ 1, \frac{1}{2} \sum_{i=1}^n (-1)^{\sigma_i} A_{ij} \right] \right)$$

It can be tightened by using properties of the constraints!



# Putting it all together

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Transforming IP into QUBO  
Let's go to the code

<https://colab.research.google.com/github/bernalde/QuIP/blob/master/notebooks/Notebook%2005%20-%20QUBO.ipynb>



# QUBO - Examples

**Coloring with colors**  $K = \{1, \dots, k\}$

Groebner basis polynomial

$$\mathcal{S} = \{x_i^{|K|} = 1, \forall i \in V$$

$$x_u^{|K|} - x_v^{|K|} = 0, \forall (u, v) \in E\}$$

IP formulation (SAT)

$$\min_{\mathbf{x}} 1$$

$$s. t. \sum_{j \in K} x_{ij} = 1, \forall i \in V$$

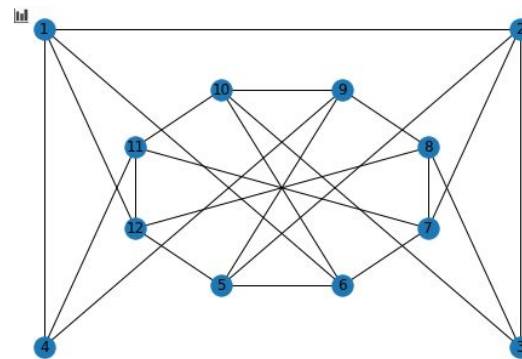
$$x_{uj} + x_{vj} \leq 1, \forall j \in K, \forall (u, v) \in E$$

$$x_{ij} \in \{0, 1\}, \forall j \in K, \forall i \in V$$

QUBO Formulation

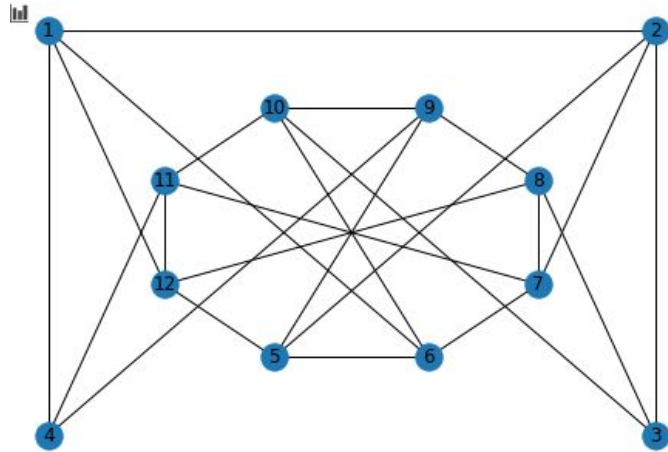
$$\min_{\mathbf{x}} \sum_{i \in V} \left(1 - \sum_{j \in K} x_{ij}\right)^2 + \sum_{(uv) \in E} \sum_{j \in K} x_{uj} x_{vj}$$
$$x_{ij} \in \{0, 1\}, \forall j \in K, \forall i \in V$$

$\mathcal{G}(V, E) =$





# QUBO for coloring initial graph



with 3 colors

<https://colab.research.google.com/github/bernalde/QuIP/blob/master/notebooks/Notebook%2005%20-%20QUBO.ipynb>



# QUBO - Quadraticization

## Algebraic geometry

### Reduction to QUBOs without slack variables

Consider the quadratic polynomial

$$H_{ij} := Q_i P_j + S_{i,j} + Z_{i,j} - S_{i+1,j-1} - 2 Z_{i,j+1},$$

with the binary variables  $P_j, Q_i, S_{i,j}, S_{i+1,j-1}, Z_{i,j}, Z_{i,j+1}$ .

- The goal is solve  $H_{ij}$  (obtain its zeros) as a QUBO (eg., using DWave)
- We can square  $H_{ij}$  and reduce using slack variables !
- Or, instead, we compute a Groebner basis  $\mathcal{B}$  of the system

$$\mathcal{S} = \{H_{ij}\} \cup \{x^2 - x, x \in \{P_j, Q_i, S_{i,j}, S_{i+1,j-1}, Z_{i,j}, Z_{i,j+1}\}\},$$

and look for a positive quadratic polynomial

$$H_{ij}^+ = \sum_{t \in \mathcal{B} \mid \deg(t) \leq 2} a_t t. \text{ Note that global minima of } H_{ij}^+ \text{ are the zeros of } H_{ij}.$$



# QUBO - Quadraticization

## Algebraic geometry

The Groebner basis  $\mathcal{B}$  is

$$t_1 := Q_i P_j + S_{i,j} + Z_{i,j} - S_{i+1,j-1} - 2Z_{i,j+1}, \quad (8)$$

$$t_2 := (-Z_{i,j+1} + Z_{i,j}) S_{i+1,j-1} + (Z_{i,j+1} - 1) Z_{i,j}, \quad (9)$$

$$t_3 := (-Z_{i,j+1} + Z_{i,j}) S_{i,j} + Z_{i,j+1} - Z_{i,j+1} Z_{i,j}, \quad (10)$$

$$t_4 := (S_{i+1,j-1} + Z_{i,j+1} - 1) S_{i,j} - S_{i+1,j-1} Z_{i,j+1}, \quad (11)$$

$$t_5 := (-S_{i+1,j-1} - 2Z_{i,j+1} + Z_{i,j} + S_{i,j}) Q_i - S_{i,j} - Z_{i,j} + S_{i+1,j-1} + 2Z_{i,j+1}, \quad (12)$$

$$t_6 := (-S_{i+1,j-1} - 2Z_{i,j+1} + Z_{i,j} + S_{i,j}) P_j - S_{i,j} - Z_{i,j} + S_{i+1,j-1} + 2Z_{i,j+1}, \quad (13)$$

in addition to 3 more cubic polynomials, (14)

We take  $H_{ij}^+ = \sum_{t \in \mathcal{B} \mid \deg(t) \leq 2} a_t t$ , and solve for the  $a_t$ . We can require that the coefficients  $a_t$  are subject to the dynamic range allowed by the quantum processor (eg., the absolute values of the coefficients of  $H_{ij}^+$ , with respect to the variables  $P_j, Q_i, S_{i,j}, S_{i+1,j-1}, Z_{i,j}$ , and  $Z_{i,j+1}$ , be within  $[1 - \epsilon, 1 + \epsilon]$ ).



# QUBO - Quadratzation

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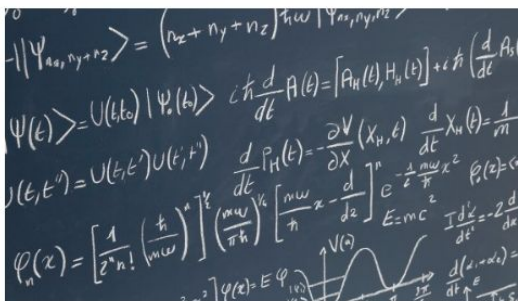
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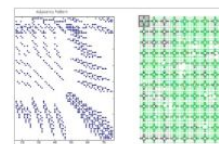
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### Quantum Annealing

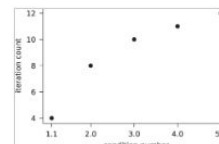
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Quantum Annealing for Prime Factorization





# Integer Factorization by Raouf and Hedayat

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Initial code

<https://colab.research.google.com/github/bernalde/QuIP/blob/master/notebooks/Notebook%2005%20-%20QUBO.ipynb>